

ELEMENTARY LINEAR ALGEBRA – SET 6

Linear mappings and matrices

1. Define the mapping $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T(x, y) = (x + y, x)$. Show that T is linear and find the matrix $M(T)$ of the mapping T with respect to the standard basis $B = \{e_1, e_2\}$ in \mathbb{R}^2 , where $e_1 = (1, 0)$ and $e_2 = (0, 1)$.
2. Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the linear mapping given by $T(x, y) = (x + y, 3x - y)$. Find its matrix in the standard basis $B = \{e_1, e_2\}$ and in the basis $B' = \{v_1, v_2\}$ given by $v_1 = (1, 1)$, $v_2 = (1, -1)$.
3. Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear mapping given by $T(x, y, z) = (x + y, y - z, x + y + z)$. Find its matrix in the standard basis $B = \{e_1, e_2, e_3\}$.
4. Define the mapping $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T(x, y) = (x + y, x + 1)$. Show that T is not linear.
5. Define the mapping $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T(x, y) = (xy, x)$. Show that T is not linear.
6. Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the linear mapping defined by the action onto basis vectors:

$$T e_1 = e_1 + 2e_2 \quad \text{and} \quad T e_2 = -e_1 + e_2,$$

where $B = \{e_1, e_2\}$ is the standard basis in \mathbb{R}^2 . Find a formula for $T(x, y)$ for any $x, y \in \mathbb{R}$.

7. For T in Problem 6 find its matrix $M(T)$ in the standard basis $B = \{e_1, e_2\}$. Representing vectors $v = (x, y)$ in terms of one-column matrices

$$M(v) = \begin{pmatrix} x \\ y \end{pmatrix},$$

verify that we have $M(T)M(v) = M(Tv)$, which gives a matrix representation of the action of T .

8. For T in Problem 6 find its matrix $M'(T)$ in the basis $B' = \{v_1, v_2\}$, where $v_1 = (1, 0)$ and $v_2 = (1, 1)$.
9. Let $T_\alpha : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the mapping given by $T_\alpha(x, y) = (x', y')$, where

$$\begin{aligned} x' &= x \cos \alpha - y \sin \alpha \\ y' &= x \sin \alpha + y \cos \alpha \end{aligned}$$

where α is an arbitrary real number. This mapping represents counterclockwise rotation of the plane by α radians about the origin. Show that T_α is a linear mapping for any $\alpha \in \mathbb{R}$. Find the images of points $(1, 0)$, $(0, 1)$, $(-1, 0)$, $(0, -1)$ under $T_{\pi/2}$. Find the matrix $M(T_\alpha)$ of T_α in the standard basis in \mathbb{R}^2 .

10. Define the linear mappings that represent

- (a) the reflection of the plane with respect to the y axis,
- (b) the reflection of the plane with respect to the x axis,
- (c) the reflection of the plane with respect to the origin.

For all these mappings find their matrices in the standard basis in \mathbb{R}^2 .

11. Let A, B be matrices defined by

$$A = \begin{pmatrix} 3 & 0 \\ -1 & 2 \\ 1 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & 5 & 2 \\ -1 & 1 & 0 \\ -4 & 1 & 3 \end{pmatrix}, \quad C = \begin{pmatrix} 1 & 1 \\ 2 & 2 \\ 0 & 1 \end{pmatrix},$$

Which of the matrices: $A+B, A+C, 2A, AB, BA, AC, CA, A^2, B^2$ are defined?
Compute these matrices which are defined.

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